# Supplementary materials

## «Microplastic monitoring in freshwater and marine surface waters using Nile red and kayak paddling - a proposed study design for citizen science»

Master study by: Kristian Louis Jensen.

Results from Linear models:

#### MP-ACT:

Linear model 1 = Particles\_pr\_m3MPACT ~ Industry Coefficients: Estimate Std. Error. P value IndustryYes 0.1929 7.3383 0.979227

Adjusted R-squared: -0.03843

Model not significant but indicates that through MP-ACT the average difference between Industry Yes and No group could be 0.193 particle per m<sup>3</sup>.

Linear model 2 = Particles\_pr\_m3MPACT ~ Inhabitants Coefficients: Estimate Std. Error P value Inhabitants 4.432e-06 1.130e-05 0.698

Adjusted R-squared: -0.03236

Model not significant but suggest that when inhabitants increase by one unit, MP ACT increases by 0.00000443 particles per m<sup>3</sup>.

Linear model 3 = Particles\_pr\_m3MPACT ~ Duration\_min Coefficients: Estimate Std. Error P value Duration of sample 0.03255 0.19912 0.871

Adjusted R-squared: -0.0374 Model not significant but indicates when duration of sampling increases by one minute, MP-ACT increases by 0.03255 particles per m<sup>3</sup>.

#### **MP-VAT:**

Linear model 1a = Particles\_pr\_m3MPVAT ~ IndustryCoefficients:EstimateStd. ErrorP valueIndustryYes-10.0467.0550.166

Adjusted R-squared: 0.03666

Model not significant but indicates that average difference between Industry Yes and No group for MP VAT is 10.046 particles per m<sup>3</sup>.

Linear model 2a = Particles\_pr\_m3MPVAT ~ Inhabitants Coefficients: Estimate Std. Error P value Inhabitants -1.180e-05 1.108e-05 0.296

Adjusted R-squared: 0.005009

Model not significant but indicates that when Inhabitants increases by one unit, MP-VAT decreases by 0.0000118 particles per m<sup>3</sup>.

Linear model 3a = Particles\_pr\_m3MPVAT ~ Duration\_min Coefficients: Estimate Std. Error P value Duration\_min -0.1218 0.1974 0.542532

Adjusted R-squared: -0.02347

Linear model not significant but indicates that when Duration increases by one unit, MP-VAT decreases by 0.1218 particles per m<sup>3</sup>.

### 1.1.1 **1. Paired t-test**

 $H0:\mu MPACT = \mu MPVATH0:\mu MPACT = \mu MPVAT$ 

H1:µmpact≠µmpvatH1:µMPACT≠µMPVAT

```
t.test(df$Particles pr m3MPACT,df$Particles pr m3MPVAT, alternative = "two.
sided",
      paired = TRUE)
##
   Paired t-test
##
##
## data: df$Particles pr m3MPACT and df$Particles_pr_m3MPVAT
## t = 1.987, df = 27, p-value = 0.05716
## alternative hypothesis: true difference in means is not equal to 0
## 95 percent confidence interval:
## -0.1809036 11.2673322
## sample estimates:
## mean of the differences
                  5.543214
##
```

P-value - 0.05716 > 0.05, there is no significance difference in two means of MPACT and MPVAT.

Nile red stained filters:



Seljord 03

# Notodden



Notodden 1 filter 1

Notodden 1 filter 2



Notodden 2 filter 1



Notodden 2 filter 2

Notodden 2 filter 3









## 1.2 Map of sampling transects

Seljord:



#### Notodden (Heddalsvannet)



#### Herøy (Frierfjorden):



(Total Q Skien)

#### Svolvær (Vågan):



#### Kabelvåg (Vågan):



Reinefjorden (Moskenes):



Bay of Gibraltar (UK):



#### Barceloneta (Surf for Science, Barcelona)

NYMM



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10,9 km/h

#### Badalona



Badalona 03

Flow-o-meter= invalid