

Decision Trees for Human Activity Recognition Modelling in Smart House Environments

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Abstract

Human activity recognition in smart house environments is the task of automatic recognition of physical activities of a person to build a safe environment for older adults or any person in their daily life. The aim of this work is to develop a model that can recognize abnormal activities for assisting people living alone in a smart house environment. The idea is based on the assumption that people tend to follow a specific pattern of activities in their daily life. An open source database is used to train the decision trees classifier algorithm. Training and testing of the algorithm is performed using MATLAB. The results show an accuracy rate of 88.02% in the activity detection task.

Keywords: *intelligent environment, behaviour modelling, pattern recognition, probabilistic model, predictive model, Norway*

1 Introduction

Human activity recognition modelling (HAM) in smart environments is an important area of research. Smart houses are being developed to improve and ease the life of the inhabitant. The idea of implementing HAM is to recognize the activities of a person in order to adapt the house to its user (Reaz, 2013; Vainio et al., 2008).

A smart house is defined as any living environment that has been carefully designed to support its inhabitant in carrying out daily activities, as well as to promote independent lifestyles (Chan et al., 2008).

People tend to follow a pattern in their daily live (Alam et al., 2010; Bourobou and Yoo, 2015). Therefore, it is possible to recognize the activities of daily life (ADL) a user performs, such as eating, toileting, bathing, dressing, etc. This recognition task is also known as human activity recognition (HAR).

Once the ADL recognition task is done, HAM can use the output from it to learn the pattern of the user and model the user's activities. The modelling has the potential to detect any deviation from the usual pattern.

Detecting abnormal activities has several applications including assisting older adults. In Norway, 38.5% of households with people aged 65 and over are living alone (sentralbyraa, 2018). Hence, a smart house can help the older adult to remain living in their own home for as long as possible (Sanchez et al., 2017).

In this work, HAR is implemented using an open source database. The output of the HAR is used for the HAM. HAM generally refers to the task of modelling the person activity pattern together with time. Therefore, accurate activity recognition is a crucial part for good HAM.

Decision trees are used to develop the HAM. Decision trees are a probabilistic algorithm that is able to predict the next step or value by learning from data. An open dataset is used for training the model.

2 Related Work

Decision tree is a supervised learning method. This method has been used for several tasks in the field of pattern recognition and machine learning as a predictive model. The main goal is to predict the next value given several input variable.

Previous studies on pervasive environment using decision trees have been successfully implemented (McBurney et al., 2008).

In smart house environments, an 80% accuracy was achieved using decision trees on 20 everyday activities in a research by Bao and Intille (2004). Another research based on decision tree with good result for ADL is the work by Fan et al. (2014).

3 Design and Methods

Figure 1 shows the methodology flow in this work.

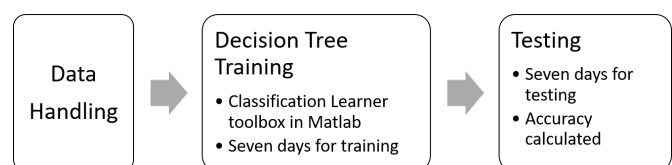


Figure 1. Methods

3.1 Decision trees

Decision trees is a hierarchical model also known as classification and regression trees. They have the property of predicting response from data.

The attributes of the decision trees are mapped into nodes. The edges of the tree represent the possible output values. Each branch of the tree represents a classification rule, from the root to the leaf node (Lara and Labrador, 2013).

3.2 Software

MATLAB is used in this study for developing the model. The classification learner toolbox was specifically used for training the tree. The code from the classification learner toolbox was exported and saved for later use with any other dataset. Testing was also coded in MATLAB.

Finally, the program Wolfram Mathematica is used for the results plots presented in this article.

3.3 Dataset

An open dataset is used in this study. The dataset has been previously used in other research and is known in the HAR field (Ordóñez et al., 2013). The dataset is named "Activities of Daily Living (ADLs) Recognition Using Binary Sensors Data Set" and is available for download at (Ordóñez, 2013). The purpose of using an open dataset is to obtain unbiased results.

The dataset consists of annotated ADLs collected by two different users living on a daily basis in a smart house. The activities in the dataset were manually labelled by the users. Table. 1 presents the dataset attributes.

Table 1. ADLs Database

<i>Name</i>	<i>Value</i>
Setting	Apartment
Number of Rooms	4 Rooms + Hall/Entrance
Number of labelled days	14 days
Labels (ADLs included)	Leaving, Toileting, Showering, Sleeping, Breakfast, Lunch, Dinner, Snack, Spare Time/TV, Grooming
Number of sensors	12 sensors
Sensors	PIR: Shower, Basin, Cook-top Magnetic: Maindoor, Fridge, Cabinet, Cupboard Flush: Toilet Pressure: Seat, Bed Electric: Microwave, Toaster

Two instances of data exist corresponding to each user living in the smart house. One dataset of 14 days (OrdóñezA), and the second dataset of 21 days (OrdóñezB). The first dataset data is depicted in Fig. 2. The first dataset

is used this work for creating and testing the model. The second dataset (OrdóñezB) is implemented later in order to test the model with a different dataset.

3.3.1 Data Handling

The variables used from the dataset are "Date", "Time", "Activity", and "Room". Another variable named "position" was added to improve the recognition task. This variable *position* correspond to one of the three following values: *laying*, *sitting*, *standing*.

Table 2 depicts the first day from the dataset. The dataset is in a text file format.

Table 2. Day 1 example of the dataset

<i>Date</i>	<i>StartTime</i>	<i>EndTime</i>	<i>Activity</i>	<i>Room</i>
28-11-11	02:27:59	10:18:11	Sleeping	Bedroom
28-11-11	10:21:24	10:23:36	Toileting	Bathroom
28-11-11	10:25:44	10:33:00	Showering	Bathroom
28-11-11	10:34:23	10:43:00	Breakfast	Kitchen
28-11-11	10:49:48	10:51:13	Grooming	Bathroom
28-11-11	10:51:41	13:05:07	Spare Time	Livingroom
28-11-11	13:06:04	13:06:31	Toileting	Bathroom
28-11-11	13:09:31	13:29:09	Leaving	Hall
28-11-11	13:38:40	14:21:40	Spare Time	Livingroom
28-11-11	14:22:38	14:27:07	Toileting	Bathroom
28-11-11	14:27:11	15:04:00	Lunch	Kitchen
28-11-11	15:04:59	15:06:29	Grooming	Bathroom
28-11-11	15:07:01	20:20:00	Spare Time	Livingroom
28-11-11	20:20:55	20:20:59	Snack	Kitchen
28-11-11	20:21:15	02:06:00	Spare Time	Livingroom

In order to model the decision tree, a sample was drawn from the dataset. All the 14 days in the dataset were stopped when the activity *leaving* was found. Seven days were used for training and seven days were used for testing.

The dataset text values were coded to numbers in order to develop the MATLAB code. Table 3 shows the *rooms* with their respective codes.

Table 3. House rooms and their code

<i>Name of Room</i>	<i>Number Assigned</i>
Bedroom	1
Bathroom	2
Kitchen	3
Livingroom	4
Hall	5

Numbers were also assigned to the *activities* to make the learning and decoding process more feasible. Table 4 shows the *activities* with the assigned codes.

Table 5 shows the coding used for the *position* values.

A total of 9 *activities*, 5 *rooms*, and 3 *positions* are used.

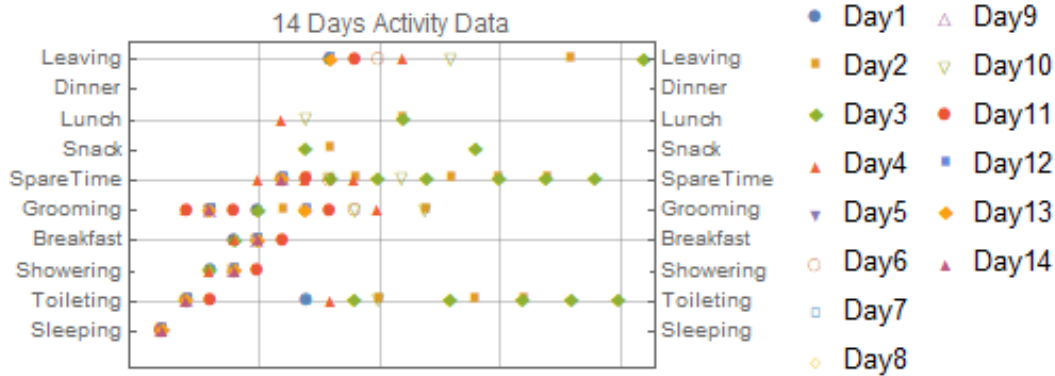


Figure 2. Activities Dataset Graph

Table 4. Activities numbers

Name of Activity	Number Assigned
Sleeping	1
Toileting	2
Showering	3
Breakfast	4
Grooming	5
Spare time/TV	6
Snack	7
Lunch	8
Leaving	9

and their code

Table 5. Position numbers and their code

Name of Activity	Number Assigned
Lying	1
Sitting	2
Standing	3

3.4 HAR Modelling (HAM)

HAM refers to the modelling of the behaviour or activity of the person. Behaviour is regarded as an activity with duration, i.e, the time elapsed from start to end of an activity and time of day (Pfeiffer et al., 2016). For example, a behaviour can be having breakfast, which consist of opening the refrigerator, cooking, sitting and eating breakfast. This set of activities are given in a time span (time elapsed from start to end), and usually in the morning (time of day).

Normal and abnormal activity and behaviour can be detected in a smart house by analysing both, the activity and the time. Abnormal activity detection main purpose is to warn a member of the family or caretaker whether something is wrong with the person. This can be regarded as anomaly. "Anomaly detection refers to the problem of finding patterns in data that do not conform to expected behavior" (Chandola et al., 2009).

4 Experiments

The dataset used in this study is available in a text file only. Therefore, the dataset was exported to an excel file. The dataset contains 14 days of data in total. Two files were created, one for training and one for testing. Random numbers was generated in MATLAB with the *randperm* function to randomly select seven days for training. The numbers selected according to the random generator were days: 12, 10, 5, 14, 1, 7, and 6. Hence, these days were use for training. The remaining days (2, 3, 4, 8, 9, 11, 13) were used for testing.

A new variable called *duration* was added. The variable *duration* was calculated using the *time* data from the dataset and consist of the time spent in each activity, from start to end of each activity. The *duration* value was calculated in seconds.

In the excel file, the text values of the dataset were coded to numbers. The variables *room*, *position* and *activities* were coded as explained in section 3.3.1. The *room* values were coded to numbers from 1 to 5. The *position* values coded to numbers from 1 to 3. The *activity* values were coded to numbers from 1 to 9.

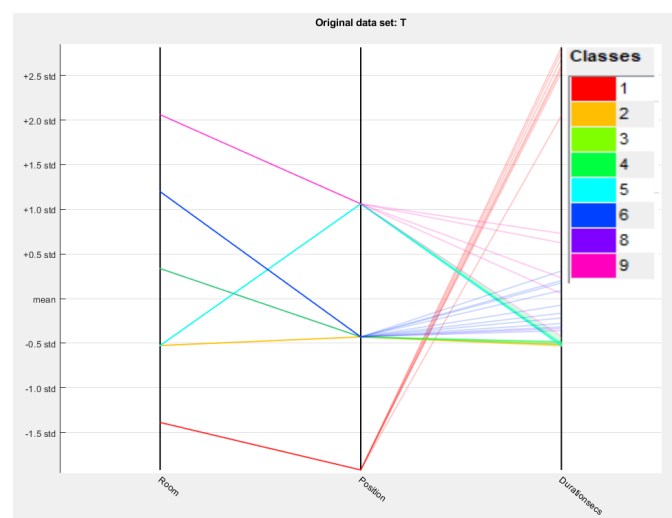


Figure 3. Parallel coordinated plots

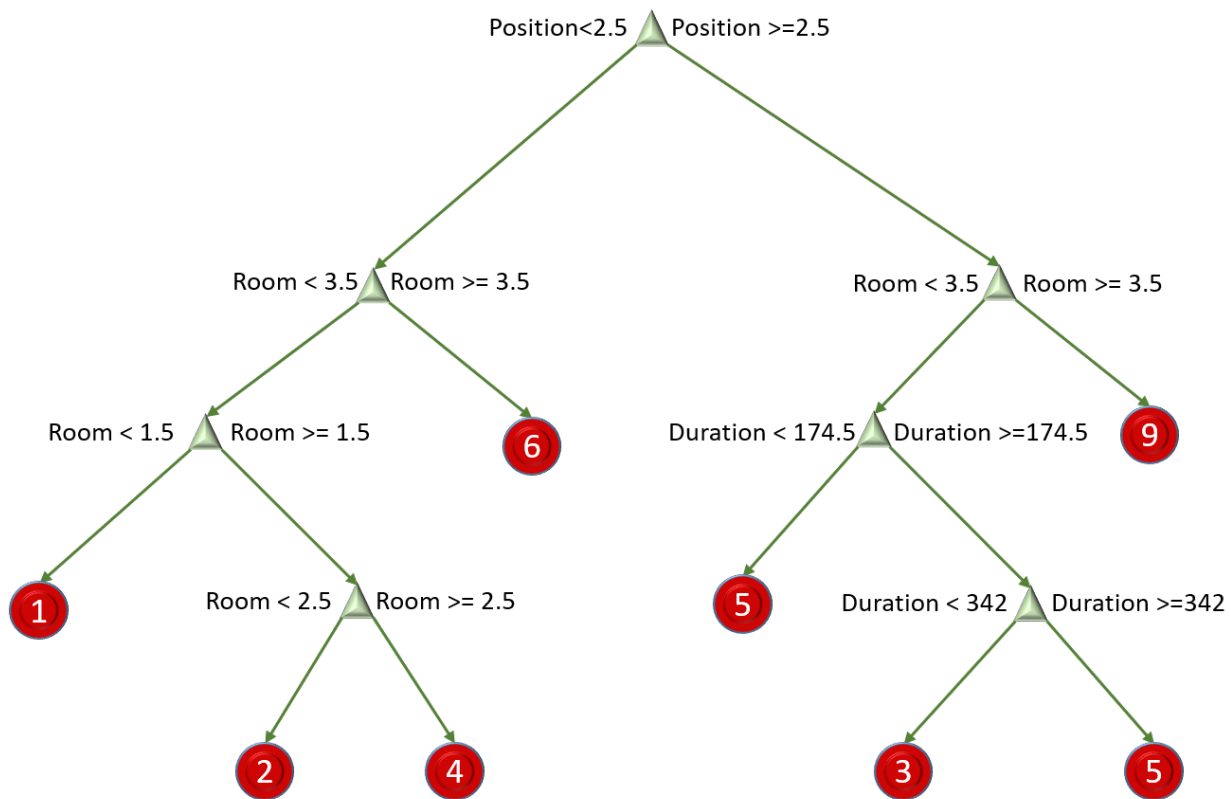


Figure 4. Trained Decision Tree. Red circles represent the activities

Both excel files were imported to MATLAB as table data type. The training was performed using the integrated classification learner toolbox. The variables used for training the decision trees are the *room*, *position*, and *duration*. The output variable is the *activity* data.

Figure 3 shows the parallel coordinated plots of the data. The variables *room*, *position*, and *duration* are plotted to show the relationship between them. According to Figure 3, it is possible to see that activities 3 and 5 (*showering and grooming*) follow almost the same path line in the graph. Also, activities 4, and 8 (*breakfast and lunch*) almost follow the same path line, with the *duration* barely different for each of the two activities. Activity 7, *snack*, was not found in the training dataset.

Once the tree is trained, testing is performed with the remaining seven days of the dataset: days 2, 3, 4, 8, 9, 11, 13. The testing consists on using the variables *room*, *position*, and *duration* as input data. The response or output is the *activity* value. Each day from the testing dataset was tested and compared to the real data.

A new fictional test set was created in order to test the model with abnormal data, as showed in table 6. The test set consists of a fictional single day. The table shows that the *duration* of some of the activities were exaggerated. In addition, the *position: lying* of the first activity in the *hall* room should qualify as abnormal behaviour.

Result plots were obtained using the Mathematica software. The actual data and the predicted data for each of

Table 6. Added test day

<i>Room</i>	<i>Position</i>	<i>Durationsecs</i>	<i>Activity</i>
Hall	Lying	10000	-
Bathroom	Sitting	15000	toileting
Bathroom	Standing	450	grooming
Living-room	Sitting	9000	spare time
Living-room	Sitting	9500	spare time
Hall	Standing	412	leaving

the testing days was copied to Mathematica and plots were coded to visually present the results.

Finally, the total computational time was measured.

5 Results

Figure 4 shows the trained decision tree. The decision tree model was able to classify seven out of nine activities in the dataset.

Figure 5 shows the number of observations for each of the activities. The true class is in the y-axis and the predicted class is in the x-axis. It is possible to see that there are no observation in the training dataset for activity number seven (*snack*), and only one observation for activity number eight (*lunch*).

Most error counts in figure 5 occurred in activities that are performed in the same *room*, such as *showering and grooming* (3 and 5). However, this number of observations

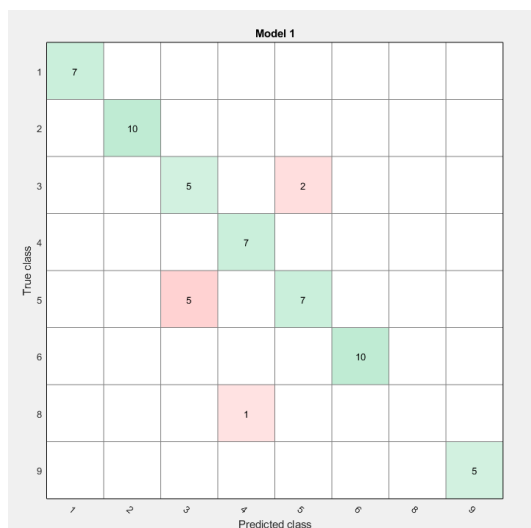


Figure 5. Number of observations

with errors is low.

Figure 6 shows in percentage of success and errors prediction in the training data, called "positive predictive values false discovery rate". The highest false discovery is 50% in the activity *grooming* (5). The model classified the activities *showering* (3) half of the times instead of the true class *grooming* (5).

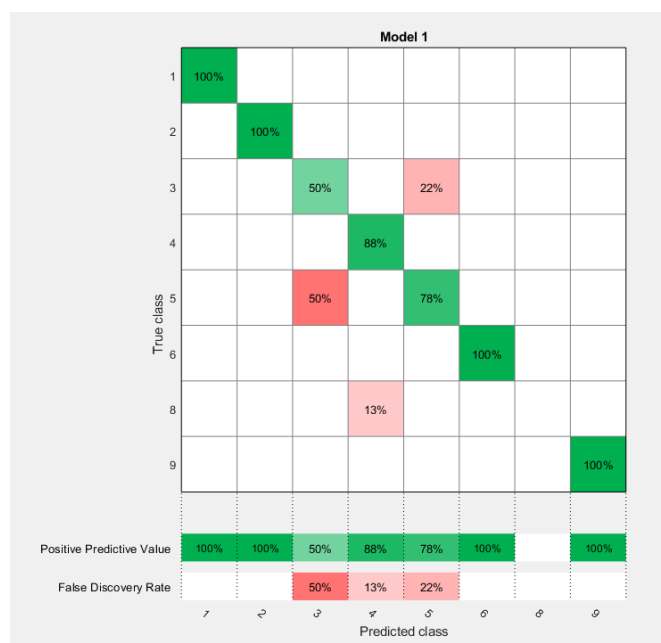


Figure 6. Positive predictive values and false discovery rates

For the activity *grooming* (5), the model had a false discovery rate of 22%, classifying the activity *showering* (3) instead of *grooming* (5).

For the activity *lunch* (8), the model classified the activity *breakfast* (4) with a false discovery of 13% .

Figure 7 shows the results of the test. Days 2, 3, 4, 8, 9, 11, and 13 were used for testing. Some prediction

errors were found when comparing the actual data with the estimated data.

Most of the errors were found between the *grooming* and *showering* activity, and between the *breakfast* and *snack* activities. A possible explanation for these prediction errors is that both of these activities are performed in the same room, *bathroom* and *kitchen*, respectively.

Figure 7h shows the results of the added fictional day with abnormal behaviour data. The model predicted the activity *Spare Time* instead of finding an abnormal behaviour in the first activity. The true positive-false posi-

Table 7. True positive \false positive rate for each activity

Activity	True Positive	False Positive
Sleeping	100%	0
Toileting	100 %	0
Showering	77%	23%
Breakfast	98%	2%
Grooming	94%	6%
Spare time	100 %	0
Lunch	36%	64%
Leaving	100 %	0

tive rate for each fo the predicted activities are shown in table 7.

Finally, the total accuracy of the activity recognition task is 88.02%. The computational time of the model, consisting of training and testing is around 3 seconds.

5.1 Test on second dataset

The model was tested on the second dataset (OrdonezB) consisting of 21 days, also open source as described in section 3.3. The purpose of this second test is to verify that the model works with any dataset.

In this test, the entire dataset was used, without sampling. The dataset was also processed as described in section 4. The values were coded to numbers. A total of 10 activities, 5 rooms and 3 positions were used.

The results showed that the model worked as well as in the experimental work (dataset Ordonez A). Like in the experimental work, minor mistakes were found in the prediction task corresponding to activities made in the same room. Namely *bathroom* and *kitchen*. Therefore, the model presented here is able to work with any dataset.

6 Discussion

In this work, decision trees are researched to perform human activity recognition modelling.

The decision tree classified seven out of nine activities. This is because there are no observation of activity *snack*, and only one observation for activity *lunch* in the training dataset. Therefore, the model could only classify seven activities in total.

Some predictions presented minor error rates. One possible reason for the these error rates is that there are rooms

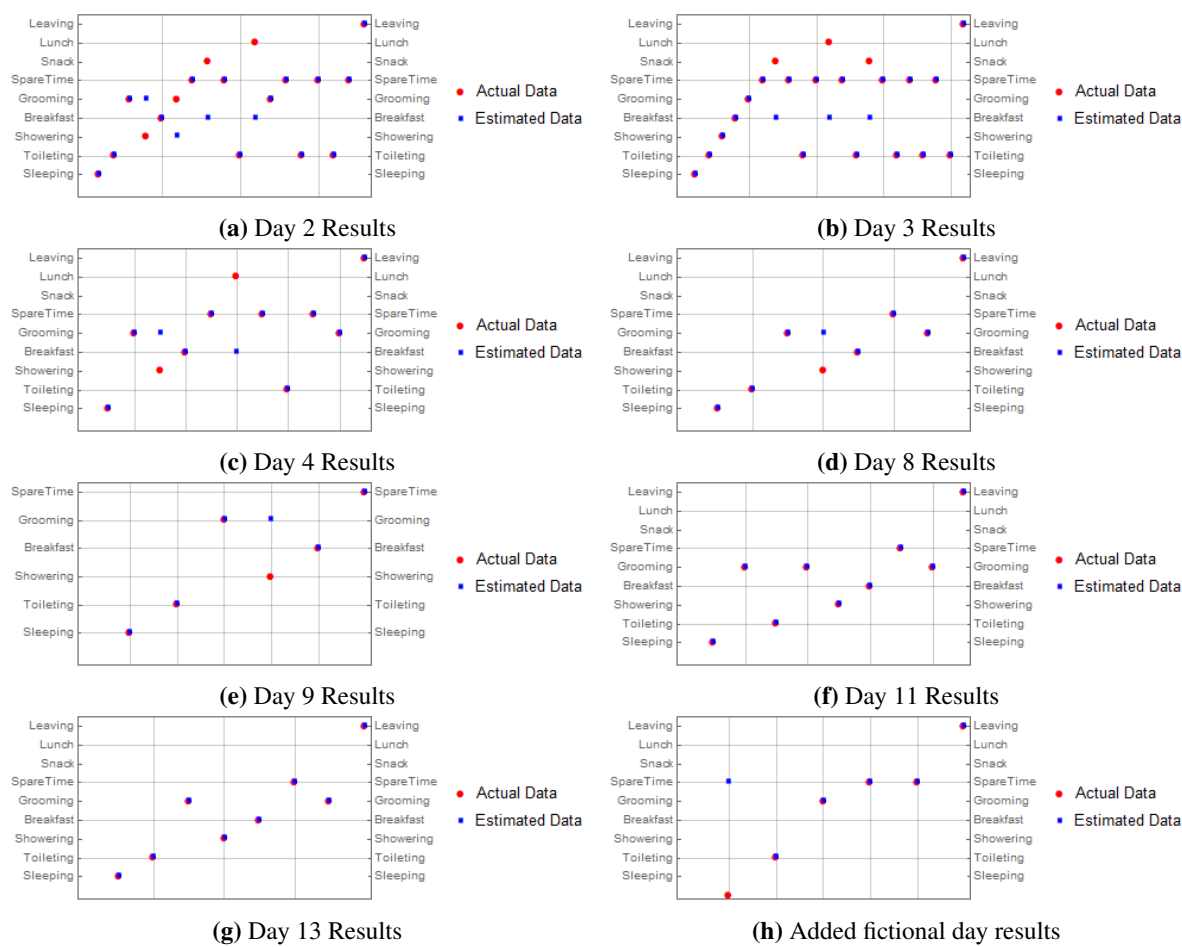


Figure 7. Results

that allow different types of activities. Hence, the recognition task is more difficult. For example, in the room *bathroom*, three different activities are performed: *showering*, *toileting* and *grooming*. Thus, the model tends to predict the highest probability of the *activity* given the room *bathroom*.

This is the same case for the room *kitchen*, where activities *breakfast*, *lunch* and *snack* are performed. The activity *lunch* has an error rate of 64%. From figure 5 it is possible to see that there is only one observation of the activity *lunch*. Therefore, the model would hardly predict this activity. Instead, the model predicts the activity *breakfast*, because it has the highest probability.

Decision trees are probabilistic algorithm and thus produces some errors in the prediction task. As any probabilistic algorithm, decision trees will always chose the highest probability according to the trained data.

In general, the finding suggest that decision trees are a good tool for HAR with 88.02% accuracy. However, for the HAM, the model does not detects abnormal behaviour as well as it does HAR. When a fictional single day test set was created to check the performance on an abnormal day, the model did not meet the expectations in the anomaly detection task.

The most like reason for this, is that decision trees does

not always enforce to check every variable before estimating a results. Consequently, in the added fictional test day with room *hall* and position *lying*, the tree predicted the activity *spare time*. Thus, the tree does not check for yhe other variables of *room*, nor *duration*. The model should have detected an abnormal behaviour in this scenario, since *lying* in the *hall* is not a normal activity, but a possible fall.

Another reason for the model not detecting abnormal behaviour is that abnormal situations need to be trained in decision trees. This means that all possible abnormal scenarios need to be learned *a priori*. As a result, the finding suggest that decision trees are not the best option for detecting abnormal activities or behaviour.

The model was also tested with the second dataset available (OrdonezB) to verify that the model is able to work with any dataset. The results obtained were similar to the experimental work. Minor mistakes were found in activities performed in the same room.

Possible solutions for improving the model are more research on how to enforce the decision trees to check every single parameter. Another option could be to combine decision trees with another probabilistic method to increase the accuracy of the model.

Finally, HAM would ideally keep the activity history of

the user in order to model the behaviour of the person. For example, if the user has followed the pattern *wake up, toiletting, grooming, showering and breakfast*, the most normal behaviour would be not to repeat any of those activities again within a given frame time.

7 Ethics in Smart Houses

Smart house technology, like any other type of technology, can carry many ethical challenges. Therefore, a separate study has been carried at USN to address this topic. We consider that the ethical aspects are an important part of our research in smart house technology.

Among the main challenges found that smart houses presents are cost-effectiveness, privacy, autonomy, informed consent, dignity, safety, and trust (Sánchez et al., 2017).

These challenges are central to keep in mind when developing a smart house system. Developers need to be aware of these challenges in order to provide a safer and dignified environment for the users. Nevertheless, it is important to acknowledge that smart house systems, at some point, cannot solve all the problems that are related to ageing, disabilities and diseases. There are needs that people develop as they age and smart house technology cannot help them any more (Sánchez et al., 2017).

8 Conclusion and Future work

In this study, activity recognition modelling (HAM) is researched. The goal is to find the normal and abnormal behaviour of the person living in a smart house. Decision trees have been used to perform activity recognition because they can predict responses to data. The output from the activity recognition task is used as an input for the modelling task.

The input data for the decision trees learning task are the *rooms, duration* and *position*. The responses are the *activities*. A total accuracy of 88.02% was achieved for activity recognition using decision trees. Thus, decision trees can be a good tool for activity recognition. However, HAM did not meet the expected results.

The reason for this is that decision trees does not enforces to verify every single input variable before calculating a result. Therefore, more research on how to check every variable before estimating a results needs to be studied. Alternatively, combining decision tree algorithm with another probabilistic model could be a possible solution for HAM.

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